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## Accounting for spatial autocorrelation in deforestation modelling (and forecasting)



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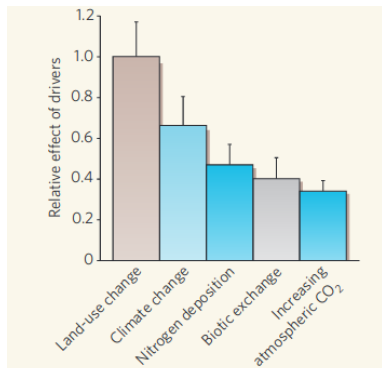
# Motivation

## Consequences of deforestation

- Biodiversity loss
- Carbon emissions and climate change

## Modelling deforestation

- Scenarios of biodiversity (IPBES) and CO<sub>2</sub> emissions (IPCC)
- Anticipate and take action (ex. policies)



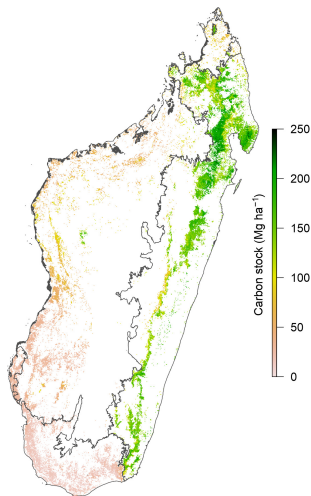
**Figure 1 | The main factors, or 'drivers', affecting biodiversity.**

Thuiller 2007, *Nature*

# Focus

## Location of deforestation

- How much deforestation? (deforestation rates)
- Where deforestation occurs preferentially?
- Biodiversity and carbon stock vary spatially



Vieilledent et al. 2016, *J. of Ecol.*

# State of art

## Model

- $Y_i \in \{0, 1\}$
- $Y_i \sim \text{Bernoulli}(\theta_i)$
- $\text{logit}(\theta_i) = f(\text{spatial factors}_i)$

## Spatial factors

- **Landscape** : distance to forest edge
- **Accessibility** : altitude, slope, distance to road, town
- **Land-policy** : protected area network

# Research gap

## Unmeasured factors

- Many other explicative spatial factors
- Population density, soil, geographical barriers, controls...
- Some **not measured**, some **unmeasurable**

## Proposed model

- $\text{logit}(\theta_{ij}) = f(\text{spatial factors}_i) + \rho_j$
- Spatial random effects  $\rho_j$  to account for unmeasured factors

# Objective

## Model comparison

- Model 1 :  $\text{logit}(\theta_{ij}) = f(\text{spatial factors}_i)$
- Model 2 :  $\text{logit}(\theta_{ij}) = f(\text{spatial factors}_i) + \rho_j$

## Challenge

- Use the model for forecasting (not only for inference)
- On large spatial scale

# Data

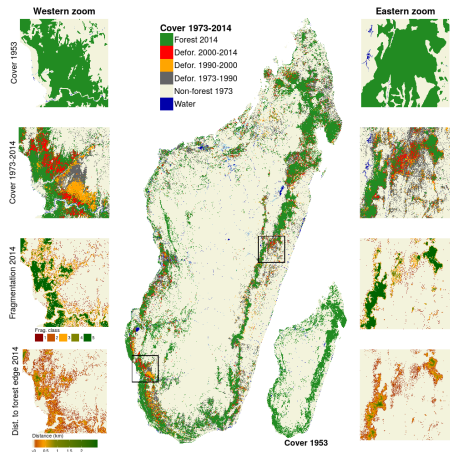


Deforestation process in Madagascar. Current rate : 100,000 ha/yr.

# Data

## Response variable

- $Y_i \in \{0, 1\}$
- Deforestation in Madagascar on the period 2000-2010
- 30 m resolution
- 20,000 points  $i$  (deforested/non-deforested)



Vieilledent et al. 2018 *Biol. Conserv.*



# Data

## Explicative variables

Product	Source	Variable derived	Unit	Resolution (m)
Deforestation maps (1990-2000-2010)	Vielledent et al. 2018	distance to forest edge	m	30
		distance to past deforestation	m	30
Digital Elevation Model	SRTM v4.1 CSI-CGIAR	altitude	m	90
		slope	°	90
Highways	OSM - Geofabrik	distance to roads	m	150
Places		distance to towns	m	150
Waterways		distance to river	m	150
Protected areas	Rebloma	presence of protected area	-	30

# Model

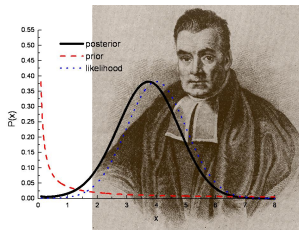
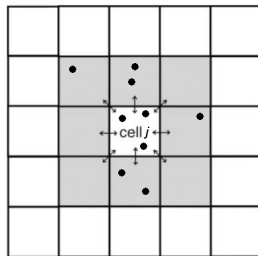
## Spatial model

- $\text{logit}(\theta_{ij}) = f(\text{spatial factors}_i) + \rho_j$
- $\rho_j$  : 10 km resolution ( $\sim 1500$  cells  $j$ )

## Intrinsic CAR

$$p(\rho_j | \rho_{j'}) = \mathcal{N}ormal(\mu_j, V_\rho / n_j)$$

$\mu_j$  : mean of  $\rho_{j'}$  in the neighborhood of  $j$ .  
 $V_\rho$  : variance of the spatial random effects.  
 $n_j$  : number of neighbors for cell  $j$ .



# Software

## Python deforestprob package

- Efficient geoprocessing on (very) large rasters
- Sampling, inference, and spatial projection
- Gibbs sampler in C using Metropolis algorithm
- GitHub : <https://github.com/ghislainv/deforestprob>

## Usable in R

- reticulate R package
- Access to Python functions and objects
- Plotting



## Parameter estimates

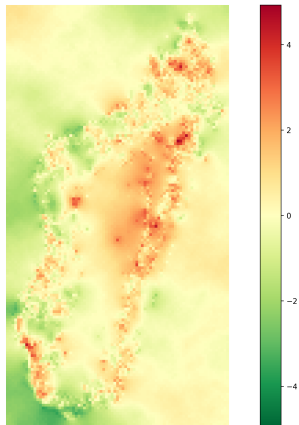
Parameter	GLM		iCAR	
	Mean	SE	Mean	SE
Intercept	0.0112	0.020	-0.705	0.108
protected area	-0.3747	0.034	-0.549	0.0694
altitude	-0.1774	0.019	-0.662	0.0713
slope	-0.1166	0.018	-0.147	0.0255
dist. defor	-0.7537	0.031	-0.869	0.0546
dist. defor <sup>2</sup>	0.0750	0.005	0.0734	0.00595
dist. edge	-0.3711	0.024	-0.51	0.0366
dist. road	-0.0006	0.016	-0.101	0.0464
dist. town	-0.0938	0.016	-0.0168	0.0424
Vrho	-	-	7.49	0.512

Small changes in parameter estimates, but same sign ( $\pm$ ) and relative magnitude.

Intuitive effects. Both models are rather good for explanatory modeling.

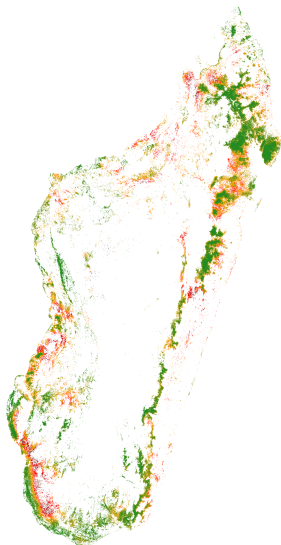
# Spatial random effects

- Hotspots of deforestation
- Not explained by the fixed env. factors



# Spatial probability of deforestation

- Computed at 30 m resolution
- Greener : lower probability
- Darker red : higher probability



# Model performance

Based on the 20,000 observations

- GLM explains only 8% of the deviance
- iCAR model better whatever the index
- GLM closer to the null model

Index	null	GLM	iCAR
Deviance expl. (%)	0	8	30
OA (%)	50	62	79
Kappa (%)	0	24	58

# Forecasting power

- Map of probability of deforestation in 2010 + known deforested area on 2010-2014
- Observed vs. projected deforestation on 2010-2014
- Area deforested in  $10 \times 10$  km areas

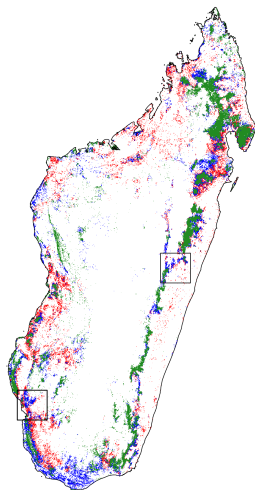
Index	GLM	iCAR
Pearson corr.	12%	31%



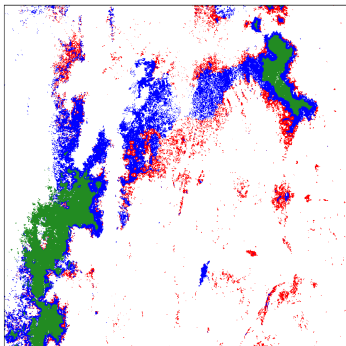
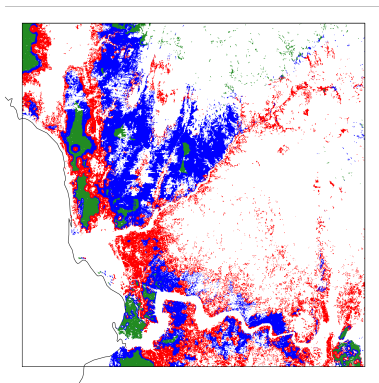
# Comparing long term forecast

## Deforestation 2010-2050

- Assuming deforestation of 100,000 ha/yr (current rate)
- green : residual forest in 2050
- red : deforested area 2010-2050
- blue : differences in model predictions



# Comparing long term forecast



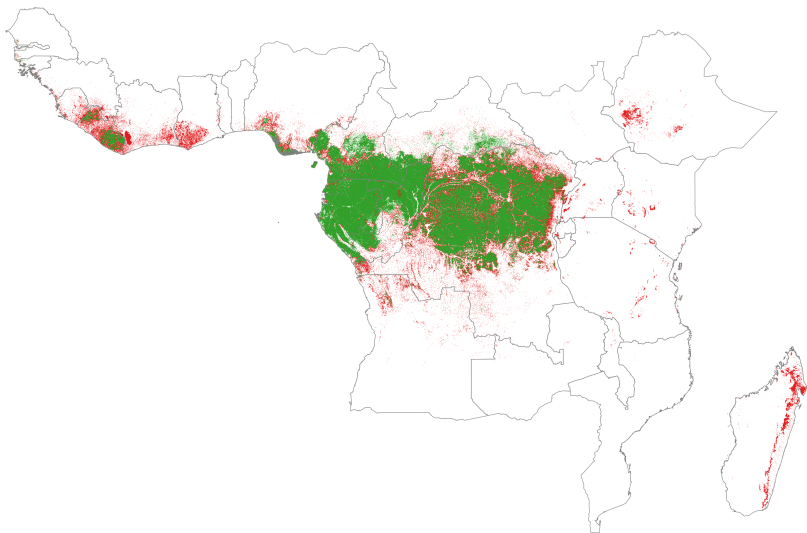
# Advantages of the iCAR model

- Account for unmeasured or unmeasurable factors
- Spatial random effect for all cells in the landscape
- Model performance is higher
- More accurate projections

# Limitations

- Better, but still with a lot of uncertainty
- Random effects can stand for many different factors
- Do they last in time (ex. people migration) ?
- It is always better to include fixed effects if possible


# Extending work to the world humid tropical forest



# Tropical forest conservation

- Tropical forests are disappearing at an alarming rate
- Engage for forest and biodiversity conservation
- Tarzan will tank you !





... Thank you for attention ...